

Some Pitfalls to Consider When Designing a TRNG

Grégoire Gimenez 2024/11/20

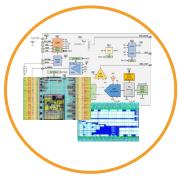


In-house Design Expertise

Analog & digital Embedded computing (ARM, RISC-V, ...)

Sensor / transducers interfaces

Power management, energy harvesting



ISO 13485 Santé Médical AFNOR CERTIFICATION

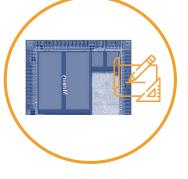
Turnkey Project

Prime contractor, taking full responsibility for milestone deliveries from idea/spec/RTL

IC'Alps in a Nutshell

Design & Back-end services for ASIC or IP level

A-la-carte – Start & stop to complement customers' team



Hardware security



Certified QMS

First-time-right project execution
Full traceability



Medical (Implantable devices, ultrasounds, ...)
IoT/AI, Industrial, Automotive, Mil/Aero, Identity & Security



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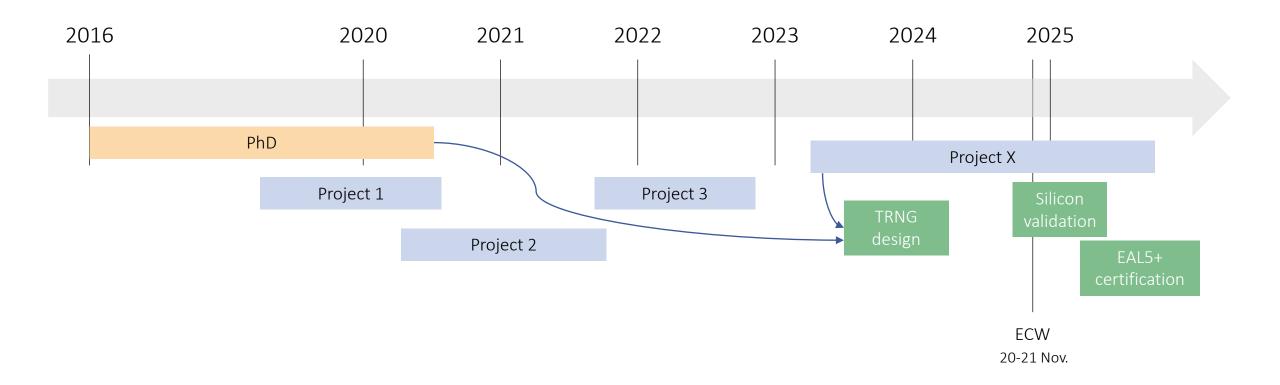




ISO 9001



About this Presentation

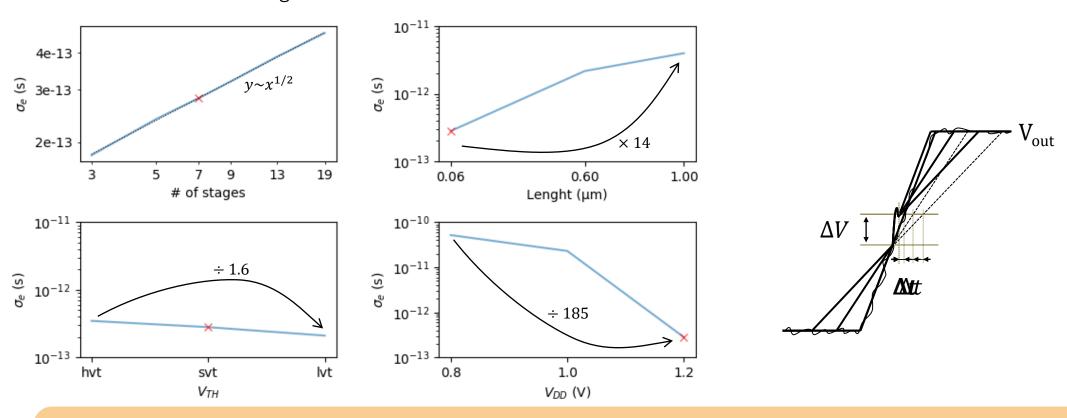


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Noise Amplification

Edge Jitter vs Parameters

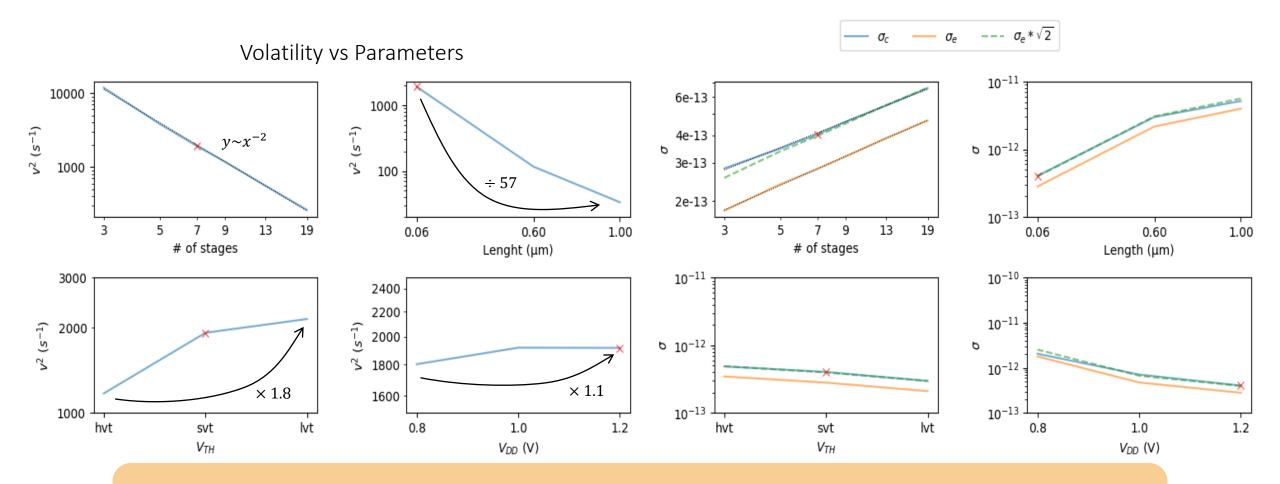


TIPS #1:

Do not hesitate to play with design parameters, there's room for optimization.

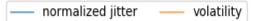


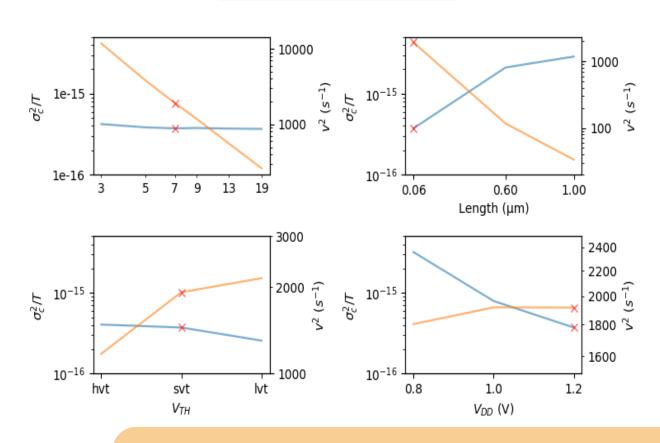
Did You Say Jitter?

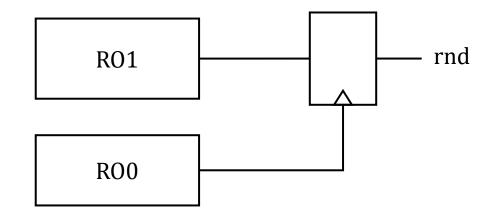


TIP #2:
Don't be fooled by the jitter, look at what matters for your design.

About Quality Factor







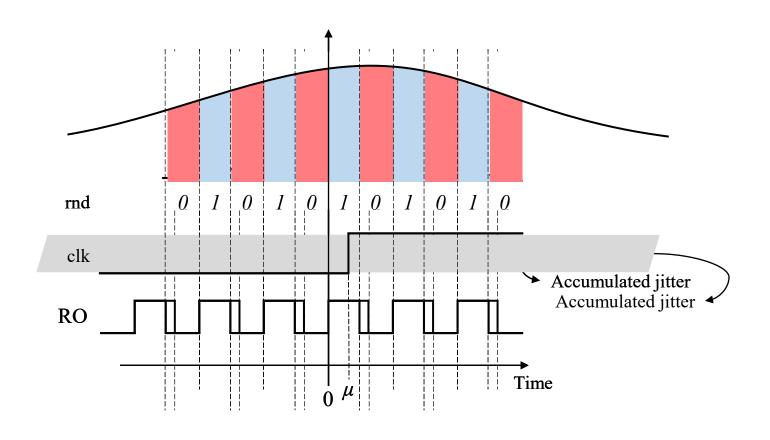
$$Q = T_0 \frac{\sigma_1^2}{T_1^3} + \frac{\sigma_0^2}{T_1^2} = T_0 \left(v_1^2 + \frac{1}{T_1^2} \frac{\sigma_0^2}{T_0} \right)$$

TIP #3:

The quality factor is useful for comparing architectures and identifying optimal parameters, but...



Some Intuitions about Randomness



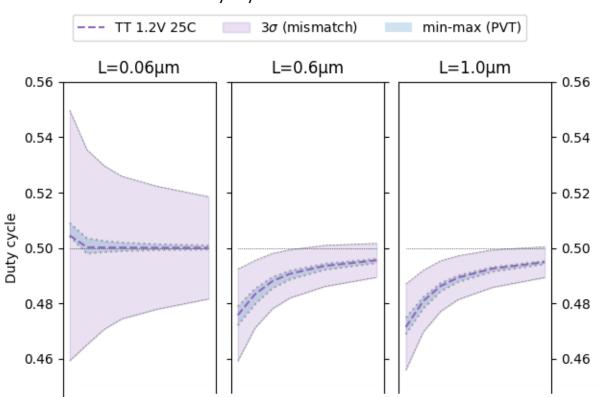
TIP #4:

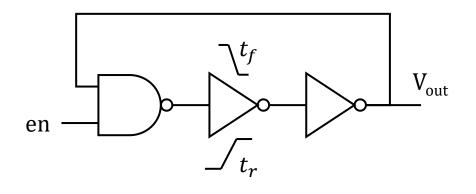
You must not forget the duty cycle.



Duty Cycle, the Troublemaker?

Duty Cycle vs Parameters





$$DC = \frac{1}{2} + \frac{t_r - t_f}{2N(t_r + t_f)}$$

$$DC = \frac{t_{rN} + \sum_{1}^{N-1} t_{f2i} + t_{r2i-1}}{\sum_{1}^{N} t_{fi} + t_{ri}}$$

TIP #5:

Worst-case estimates based on PVTs alone are not sufficient. Use mismatch simulation instead.

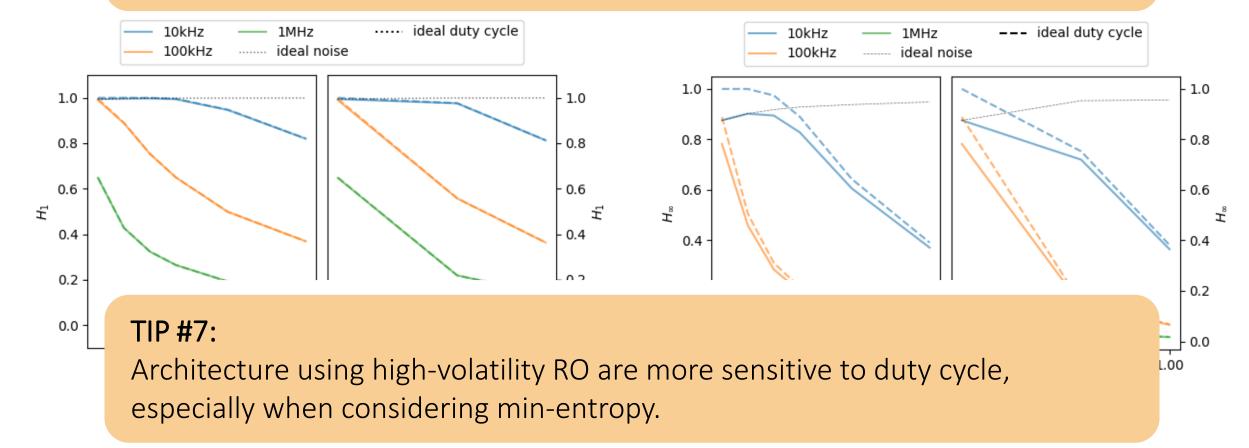
0.44



A Bit of Entropy

TIP #6:

It is (very) difficult for a single oscillator based architecture to meet such entropy rate targets.





Conclusions

- Designing a TRNG is not trivial
 - Many design choices are possible and should be investigated when performance/power/area are targeted
 - Different parts of an entropy source require different optimizations
- Impact of duty cycle on the entropy should not be underestimated
 - Duty cycle should be correctly estimated with monte-carlo simulations
 - We should use stochastic models that takes duty cycle as input parameter
 - Architectures with few high volatility (XORed) ROs are very sensitive to duty cycle
 - They may require internal measurement (and monitoring?) of the duty cycle
 - Architectures with many low volatility (XORed) ROs may be more efficient, but bring other concerns
- Volatility and duty cycle have opposite trends. It limits the design space.
- These conclusions drawn from a 55nm study, but mostly applicable in any technology node
- Some open questions :
 - Discrepancy between models
 - Are there any correlations between two successive periods for small/large L/starved rings?
 - Defining a quality factor reunifying both jitter and duty cycle would help strike the right balance



Reference

- [Saarinen21] M. J. O. Saarinen « On entropy and bit patterns of ring oscillator jitter ». In: 2021 Asian Hardware Oriented Security and Trust Symposium (AsianHOST). IEEE, 2021. p. 1-6.
- [Lubicz24] D. Lubicz and V. Fischer. « Entropy Computation for Oscillator-based Physical Random Number Generators ». *Journal of Cryptology* 37.2. 2024, p. 13.

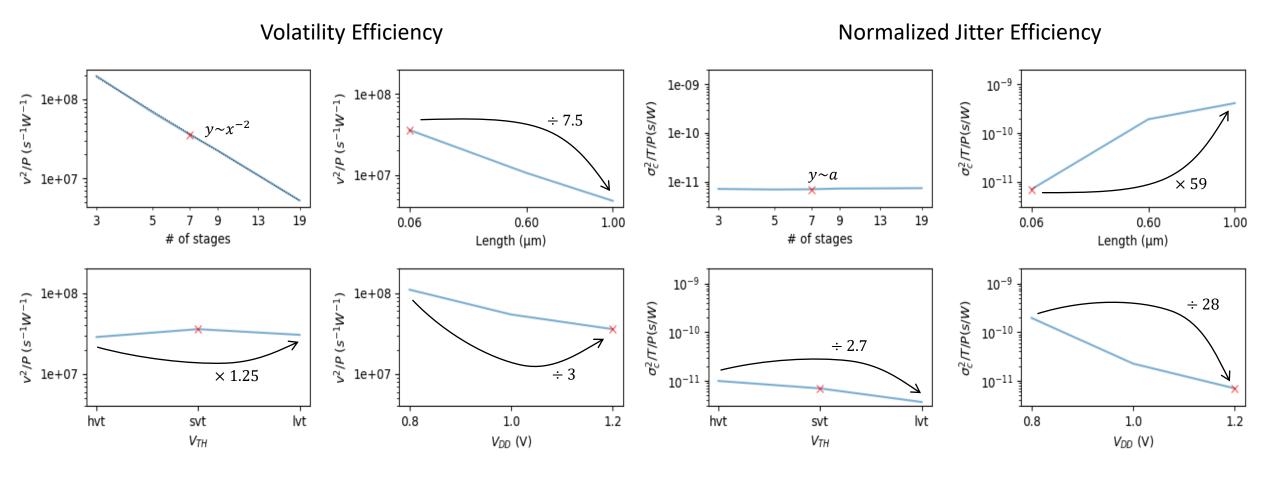








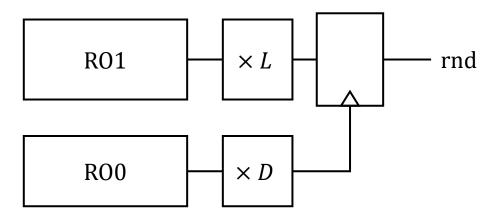
Efficiency



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Generalized Architecture

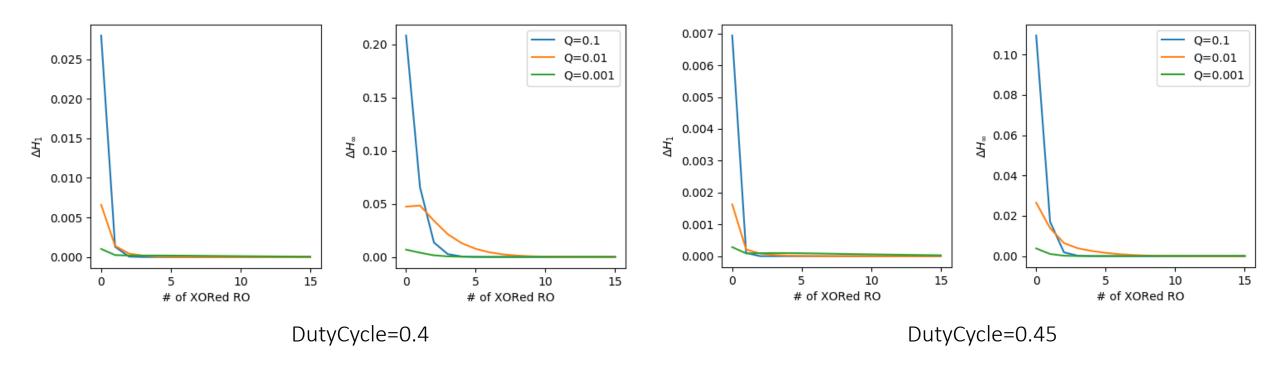


$$Q = \nu_{eq}^2 \Delta T = \frac{D}{L^2} \frac{T_0}{T_1} \times \left(\frac{\sigma_1}{T_1}\right)^2 + \frac{D}{L^2} \left(\frac{\sigma_0}{T_1}\right)^2$$
$$\nu_{eq}^2 = \frac{1}{L^2} \times \left(\nu_1^2 + \frac{1}{T_1^2} \frac{\sigma_0^2}{T_0}\right)$$



Entropy Loss due to Duty Cycle

Loss of Entropy Rate depending on the # of XORed RO*



^{*}The loss is calculated against a TRNG with ideal RO (duty cycle=0.5)